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# Experimental Analysis of 

 QEM Based MeshSimplification Techniques
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- Various applications in computer graphics need complex and detailed models for providing reality.
- For this reason, models are captured with high resolution but complexity of the model causes an increase in the computational cost.
- To solve this issue, producing simpler forms of such models has gained great importance.



Schroeder et al. [1992]
Decimation of Triangle Meshes


Garland and Heckbert [1997]
Surface Simplification Using Quadric Error Metrics


Garland and Heckbert [1998]
Simplifying Surfaces with Color and Texture using Quadric Error Metrics


Tarini et al. [2010]
Practical Quad Mesh Simplification

- Our goal is to observe impacts of mesh simplification on the visual quality and storage sizes.
- For this purpose, we will use Quadric Error Metrics (QEM) based mesh simplification technique, which is already implemented in MeshLab.
- We will evaluate simplification with ten different objects and analyze results in terms of categories like data size, number offaces and PSNR differences between simplified mesh model and original model.



## Vertex Decimation Based Techniques


borders


Vertex Classifications

important edges


Triangulation

Problem: Works slowly


Low and Tan [1997]
Model Simplification Using Vertex-Clustering


Hua et al. [2005]
Model Simplification Using Vertex-Clustering Based on Principal Curvature

## QEM Based Techniques



Garland and Heckbert [1997]
Edge Contraction


Before


Garland and Heckbert [1997] Non-Edge Contraction

## QEM Based Techniques



Tang et al. [2010]
The edge contraction based on midpoints

(a) Proposed method

(b) Garland and Heckberts' method

(c) Maximo et al.'s method

Yao et al. [2015]
QEM mesh simplification based on discrete curvature


Hoppe [1999]
It's faster than previous techniques at the same accuracy


Garland and Heckbert [1997]
Edge Contraction


Before

- In this study, we use a QEM based algorithm that depends on iterative contraction of vertex pairs. It is a generalization of iterative edge contraction.
- In this technique, pair selection is important issue and valid pairs $\left(\mathbf{v}_{1}, \mathbf{v}_{2}\right) \rightarrow$ $\overline{\mathbf{v}}$ should be defined according to two rules:
- $\left(\mathbf{v}_{1}, \mathbf{v}_{2}\right)$ pair should create an edge.
- $\left\|\mathbf{v}_{1}, \mathbf{v}_{2}\right\|<t$, where $t$ is a threshold parameter.


## Our QEM Based Technique

- After deciding all valid pairs, cost of each contraction is computed. To do this, a symmetric $4 \times 4 \mathbf{Q}$ matrix is assigned with each vertex.
- Error formula is written as $\Delta(\mathbf{v})=\mathbf{v}^{\mathbf{T}} \mathbf{Q} \mathbf{v}$, where $\mathbf{v}=\left[\boldsymbol{v}_{\boldsymbol{x}} \boldsymbol{v}_{\boldsymbol{y}} \boldsymbol{v}_{\boldsymbol{z}} \mathbf{1}\right]^{\mathbf{T}}$.
- In order to perform contraction, $\left(\mathbf{v}_{1}, \mathbf{v}_{2}\right) \rightarrow \overline{\mathbf{v}}$, we must choose a position for $\overline{\mathbf{v}}$ which minimizes $\Delta(\overline{\mathbf{v}})$. In this selection, we use the simple additive rule for the new matrix as $\overline{\mathbf{Q}}=\mathbf{Q}_{\mathbf{1}}+\mathbf{Q}_{\mathbf{2}}$.
- The error cost of the new vertex is computed as: $\Delta(\overline{\mathbf{v}})=\overline{\mathbf{v}}^{\mathrm{T}}\left(\mathbf{Q}_{\mathbf{1}}+\right.$ $\left.\mathbf{Q}_{2}\right) \overline{\mathbf{v}}$. Then all valid pairs are put into a minimum heap with their contraction costs.
- Lastly, the pair which has least cost is removed from the heap and costs of all valid pairs are updated iteratively.
- The only remaining issue is how to compute the initial $\mathbf{Q}$ matrices from which the error metric $\Delta(\mathbf{v})$ is constructed.
- It is observed that each vertex is created from an intersection of a set of planes with this manner. The error of each vertex is associated with this set by finding sum of squared distance to its planes as follows:

$$
\Delta(\mathbf{v})=\mathbf{v}^{\mathrm{T}}\left(\sum_{\mathbf{p}} \mathbf{K}_{\mathbf{p}}\right) \mathbf{v},
$$

where $\mathbf{p}=\left[\begin{array}{llll}\boldsymbol{a} & \boldsymbol{b} & \boldsymbol{c} & \boldsymbol{d}\end{array}\right]^{\mathbf{T}}$ is a plane associated with vertex $\mathbf{v}, \mathbf{K}_{\mathbf{p}}=\mathbf{p} \mathbf{p}^{\mathbf{T}}$ is fundamental error quadric.

- Therefore, initial $\mathbf{Q}$ matrix for vertex $\mathbf{v}$ is the sum of fundamental error quadrics $\mathbf{K}_{\mathbf{p}}$.

1. Compute the $\mathbf{Q}$ matrices for all the initial vertices by summing fundamental error quadrics $\mathbf{K}_{\mathbf{p}}$.
2. Select all valid pairs.
3. Compute the optimal contraction target $\overline{\mathbf{v}}$ for each valid pair $\left(\mathbf{v}_{1}, \mathbf{v}_{2}\right)$. The error $\Delta(\overline{\mathbf{v}})=\overline{\mathbf{v}}^{\mathbf{T}}\left(\mathbf{Q}_{\mathbf{1}}+\mathbf{Q}_{\mathbf{2}}\right) \overline{\mathbf{v}}$ of this target vertex becomes the cost of contracting that pair.
4. Place all the pairs in a heap keyed on cost with the minimum cost pair at the top.
5. Iteratively remove the pair $\left(\mathbf{v}_{1}, \mathbf{v}_{2}\right)$ of least cost from the heap, contract this pair, and update the costs of all valid pairs involving $\mathbf{v}_{1}$.

## Experimental Results

| Model | Metrics |  |  |
| :---: | :---: | :---: | :---: |
|  | \#Faces | \#Vertices | Data Size |
| Armadillo | 345,944 | 172,974 | 3.9 MB |
| Bunny | 69,451 | 35,974 | 2.89 MB |
| Dragon | 871,414 | 437,645 | 32.2 MB |
| Golfball | 245,760 | 122,882 | 2.66 MB |
| Happy Buddha | $1,087,716$ | 543,652 | 40.6 MB |
| Horse | 96,964 | 48,484 | $1,07 \mathrm{MB}$ |
| Igea | 268,686 | 134,345 | 2.96 MB |
| Lucy | 525,814 | 262,909 | 6.03 MB |
| Max Planck | 98,260 | 49,132 | 1.11 MB |
| Thai Sculpture | $\mathbf{1 , 0 0 0 , 0 0 0}$ | 499,999 | 181 MB |

Table 1: Statistics of the simplified three-dimensional models.

- In this work, we used MeshLab to analyze QEM based mesh simplification techniques, as QEM based mesh simplification techniques are already implemented in MeshLab.


## Experimental Results



Figure 1: The peak signal-to-noise ratio (PSNR) values of QEM based mesh simplification technique with different values of the compression ratio (CR).

## Experimental Results


(Data Size: 3.9 MB)
$(\mathrm{CR}=1000, \mathrm{PSNR}=22.633)$
$(\mathrm{CR}=100, \mathrm{PSNR}=28.074)$
$(\mathrm{CR}=10, \mathrm{PSNR}=34.376)$


Figure 2: A visual analysis of the QEM based mesh simplification technique on various 3D models. From top to bottom: armadillo, dragon, horse, max planck 3 D objects. While the first column represents reference 3D objects, other columns represents simplified 3D objects according to various Compression Ratio (CR) parameters. Below each simplified model, we depict false-color differences between the reference 3D models and the simplified 3D models. For better comparison, false-color differences were scaled by a factor of 5. Below each simplified 3D model, we also report PSNR values (higher is better) and CR values.

## Experimental Results


(Data Size: 1.11 MB)

$(C R=100, P S N R=31.133)$
$(\mathrm{CR}=10, \mathrm{PSNR}=37.635)$

Figure 2: A visual analysis of the QEM based mesh simplification technique on various 3D models. From top to bottom: armadillo, dragon, horse, max planck 3D objects. While the first column represents reference ${ }_{3}$ D objects, other columns represents simplified ${ }_{3}$ D objects according to various Compression Ratio (CR) parameters. Below each simplified model, we depict false-color differences between the reference 3D models and the simplified 3D models. For better comparison, false-color differences were scaled by a factor of 5. Below each simplified 3D model, we also report PSNR values (higher is better) and CR values.

## Conclusions

- We have investigated types of simplification methods such as vertex decimation, vertex clustering and iterative edge contraction using error quadric metrics.
- Vertex decimation is found to be efficient and produce good results, vertex clustering generates poor results.
- In our study, we have performed mesh simplification on different models to see visual effects of it. We have chosen iterative edge decimation method that is supplied by MeshLab.


## Conclusions

- After experiments, we have realized that when model is chosen as complex, simplification error between reference and simplified models increases much more in comparison with simpler models.
- At the same time, if we use high compression ratio, higher simplification error is reached. Hence, it could be concluded that compression ratio affects the error linearly.


## Thank You

