The 8th Eurographics Workshop on Material Appearance Modeling: Issues and Acquisition

A Genetic Algorithm Based Heterogeneous Subsurface Scattering Representation

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In this paper, we present a novel heterogeneous subsurface scattering representation, which is based on a combination of Singular Value Decomposition and genetic optimization techniques.

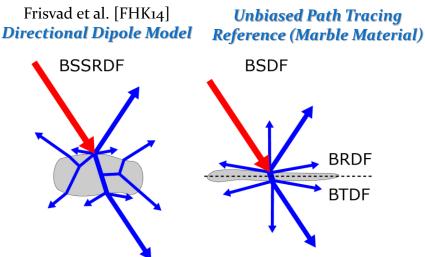
Introduction



Jensen et al. [JMLHo1] Standard Dipole Model

d'Eon and Irving [dI11] **Quantized Diffusion Model**





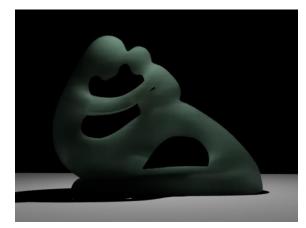
Jimenez et al. [JZJ*15]

The most of the homogeneous subsurface scattering models used in the computer tra The diffu graphics community are derived based on this approximation sused to the represent ho[JMgH01,JB02,FHK14,JZJ*15].rials [FJB04].

Introduction



Peers et al. [PvBM*o6] A factored heteregeneous model



Kurt et al. [KÖP13] A Tucker-based heteregeneous model



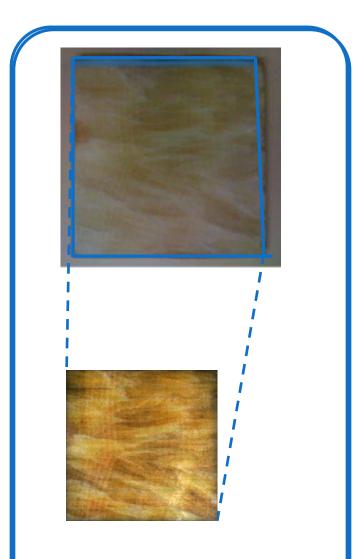
Song et al. [STPP09] SubEdit: A heteregeneous model



Yatagawa et al. [YTYM20] A compression based heteregeneous model

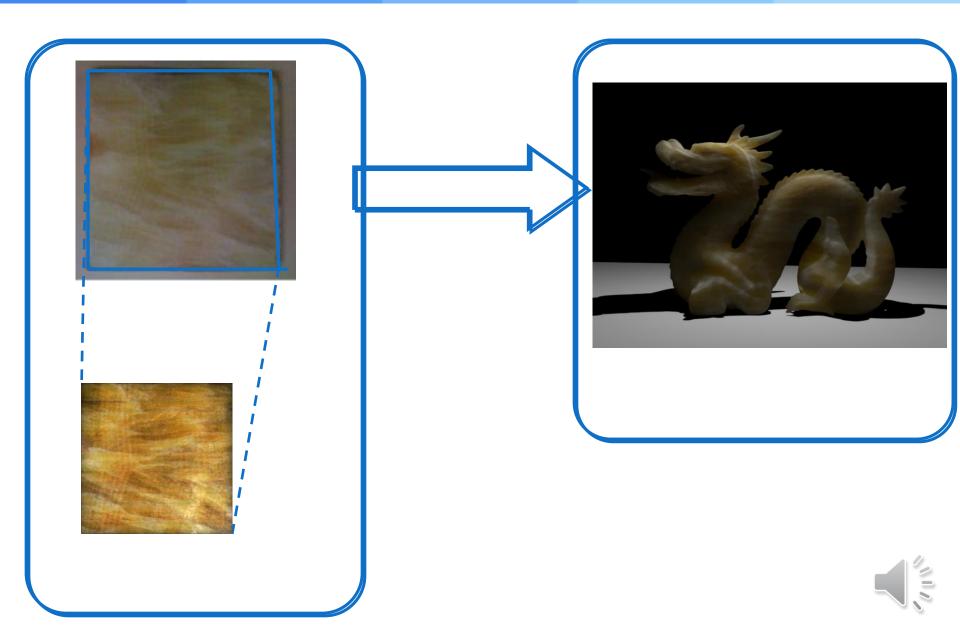
Therefore, a number of data-driven subsurface scattering representations [PvBM*06, But, Sit's Still, an investigation issue to represent measured heterogeneous subsurface heterogescattering data compactly and physically accurately.



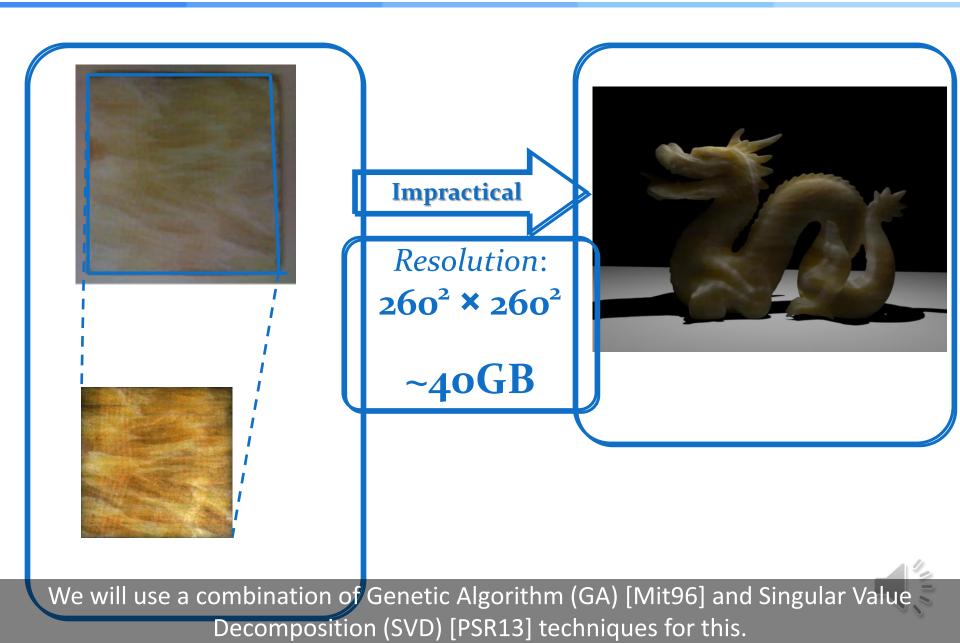


Therefore, we focus in this work on the compact and accurate representation of this spatial component of heterogeneous subsurface scattering.

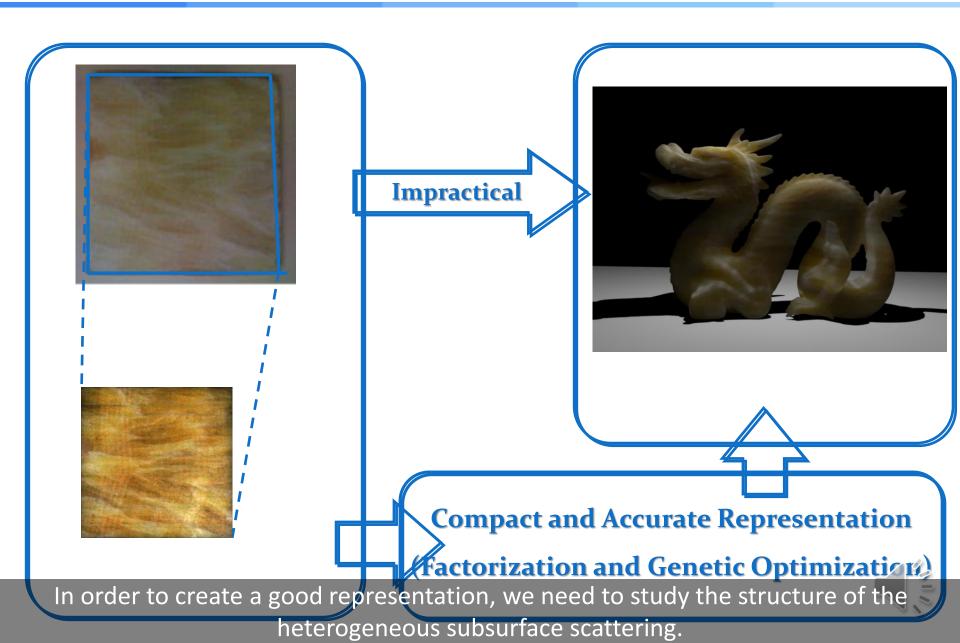




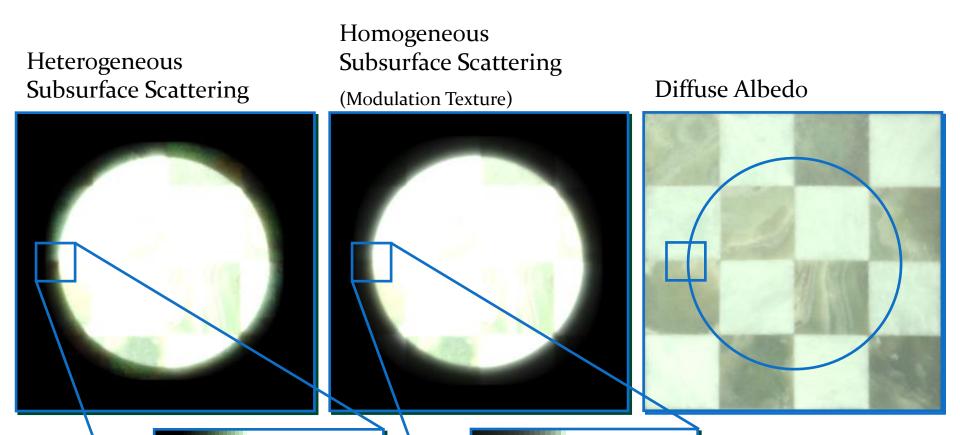








Heterogeneities: Effect



While optical properties of homogeneous translucent materials are constant, Oheterogeneous translucent materials exhibit spatially varying optical behaviors ly homogeneou [Kur20] sterogeneous.

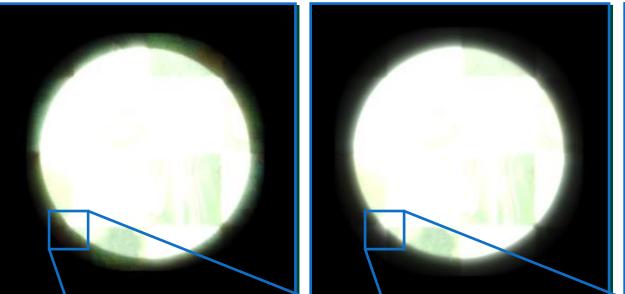
Heterogeneities: Effect

Homogeneous

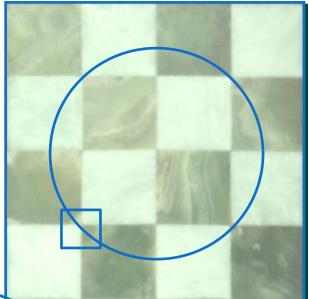
(Modulation Texture)

Subsurface Scattering

Heterogeneous Subsurface Scattering

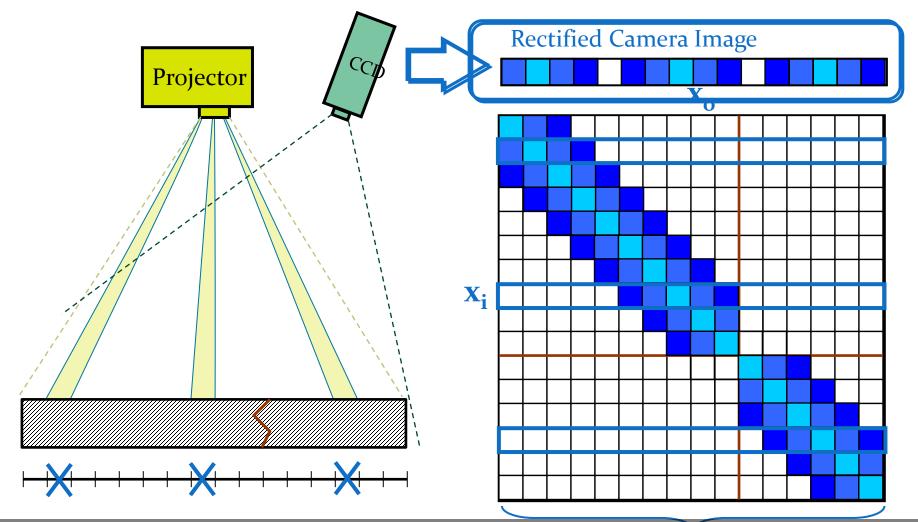


Diffuse Albedo



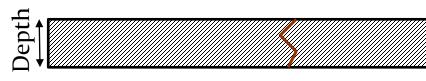
Therefore, measuring and modeling of heterogeneous translucent materials are much more complicated than homogeneous translucent materials, and requires much better understanding of light and material interactions beneath the surface.

Acquisition: Multiple Beams (1)



In this work, we used Peers et al.'s [2006] Song et al.'s [2009] heteregeneous After these operations pwe get 2D subsurface scattering matrix and this matrix can be two steps, used by the rendering algorithms earization.

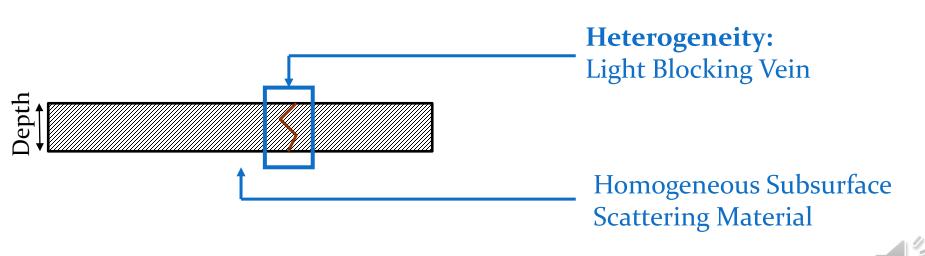
Illustrative Example (1D)



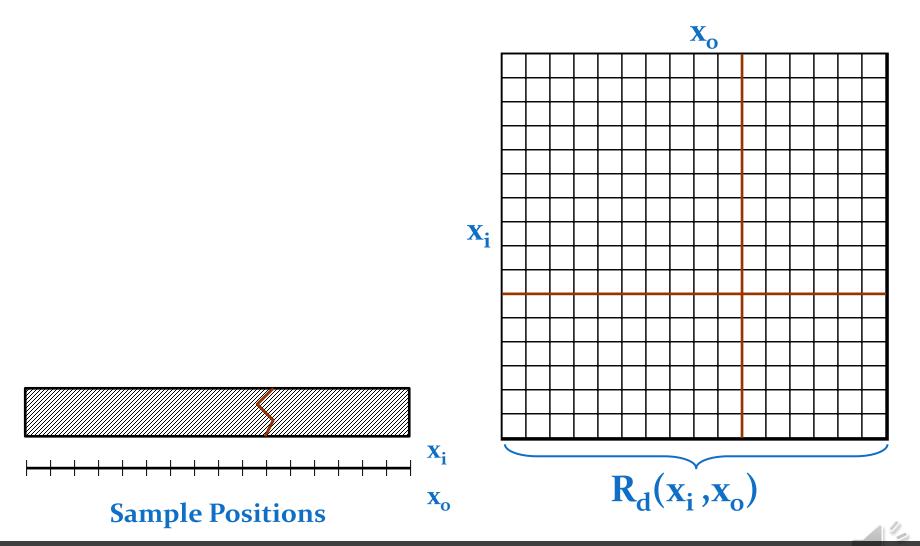
Homogeneous Subsurface

Scattering Material To show how we prepare our subsurface scattering matrix, let's consider the following 1D illustrative example: a planar sample, consisting of a single material exhibiting homogeneous subsurface scattering.

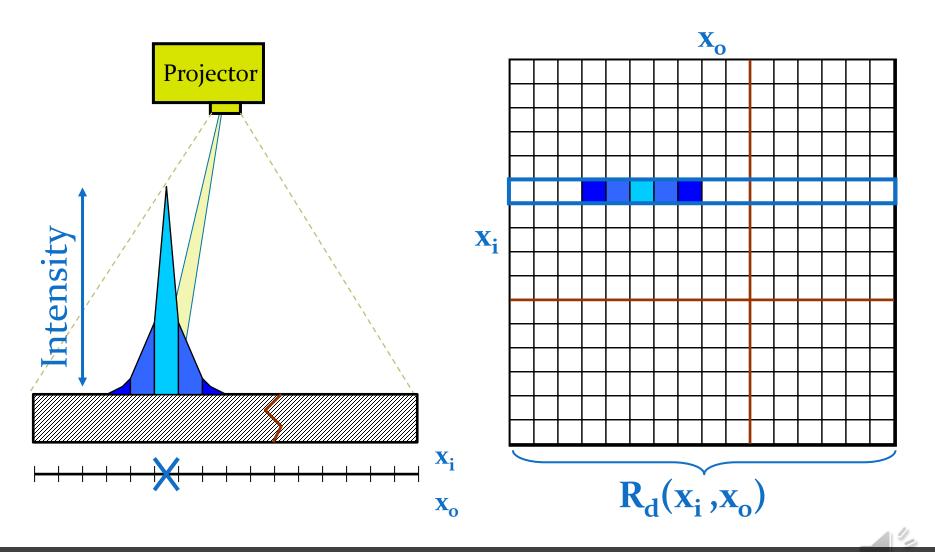
Illustrative Example (1D)



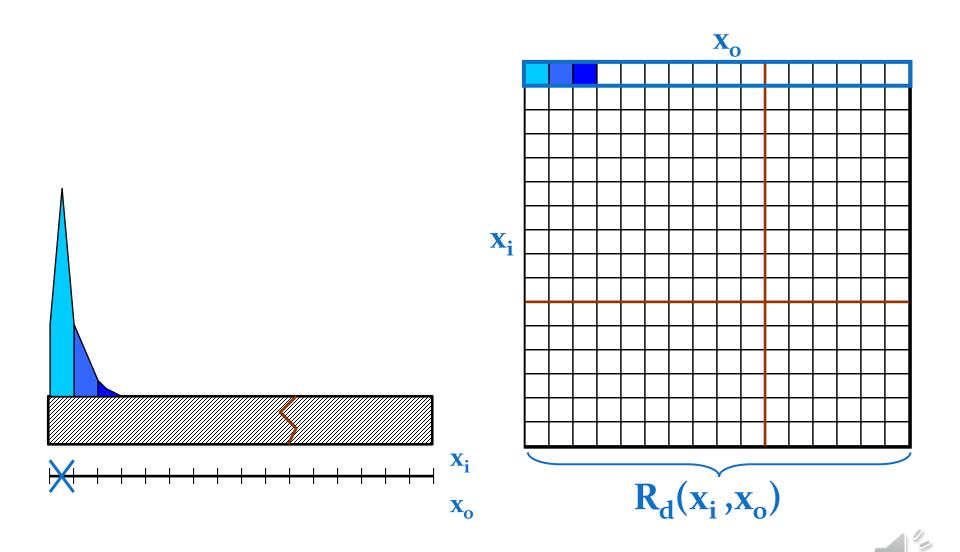
This sample contains a single heterogeneity: a light blocking vein, that blocks a light going from the left side of the sample to the right side, and vice versa.



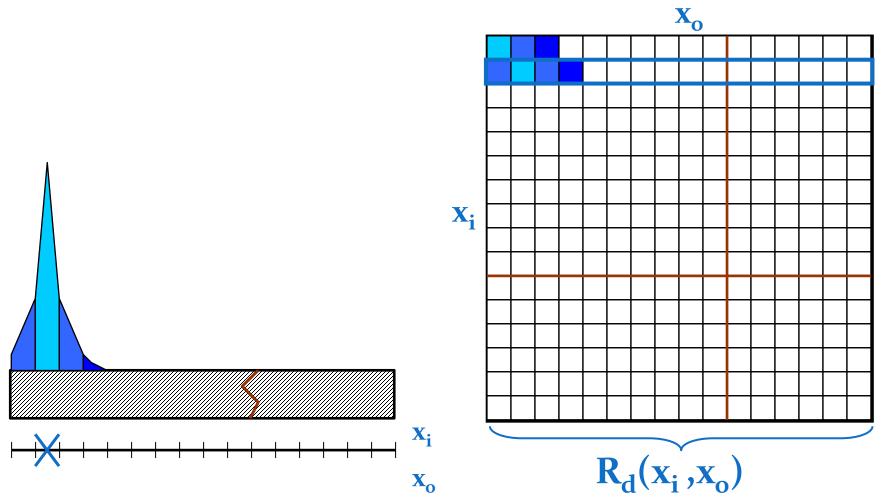
For/simplicity we assume that x<u>t</u>it and x<u>b</u>o are parameterized identically oven the parameterizes ample surface and that both have the same resolution ant point x_o.



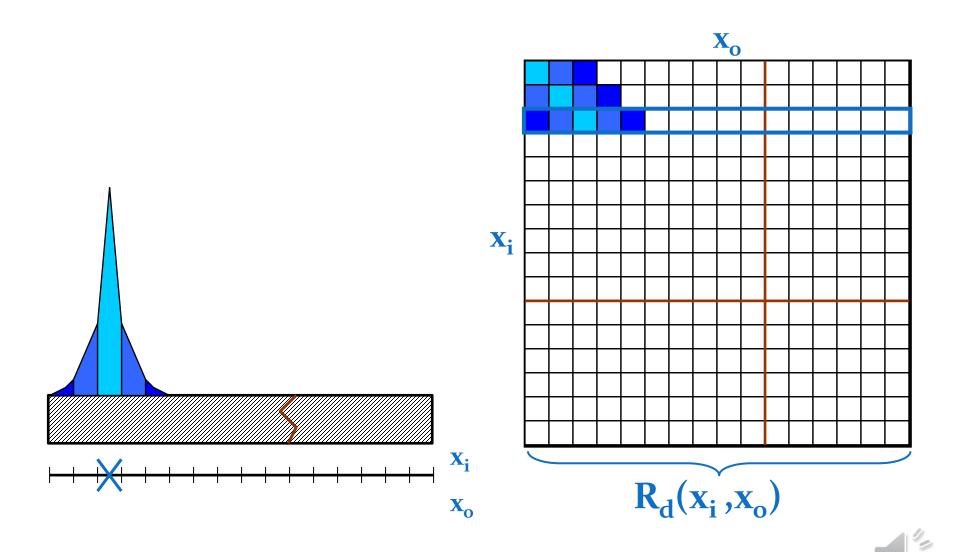
Encourcase, taiprojector was used to illuminate surface points, and the observed camera image is copied into the corresponding row of R_d.

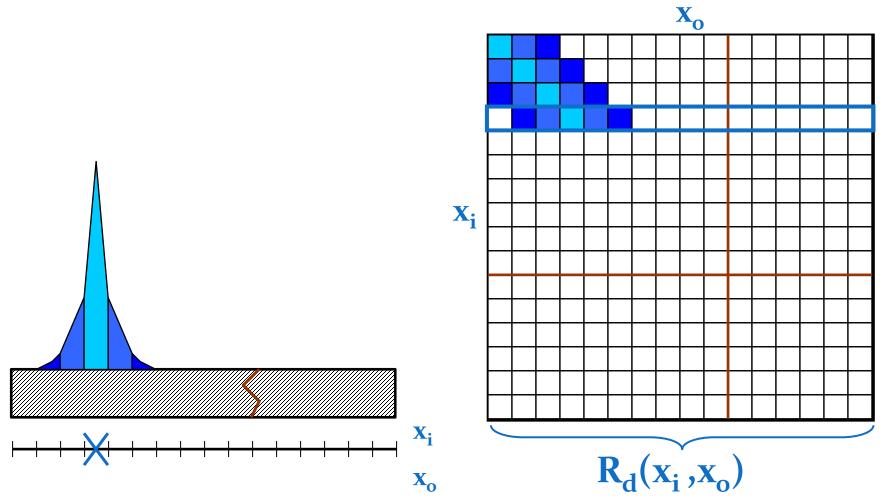


We can repeat this for every incident position and row.

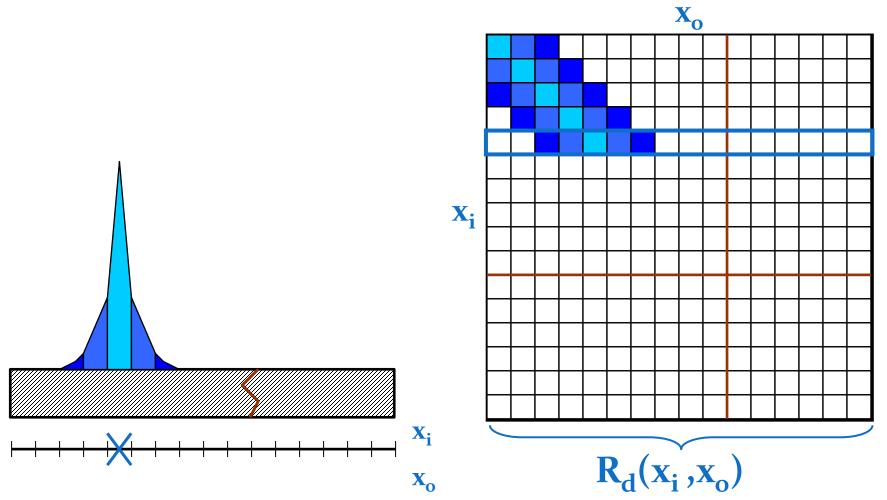




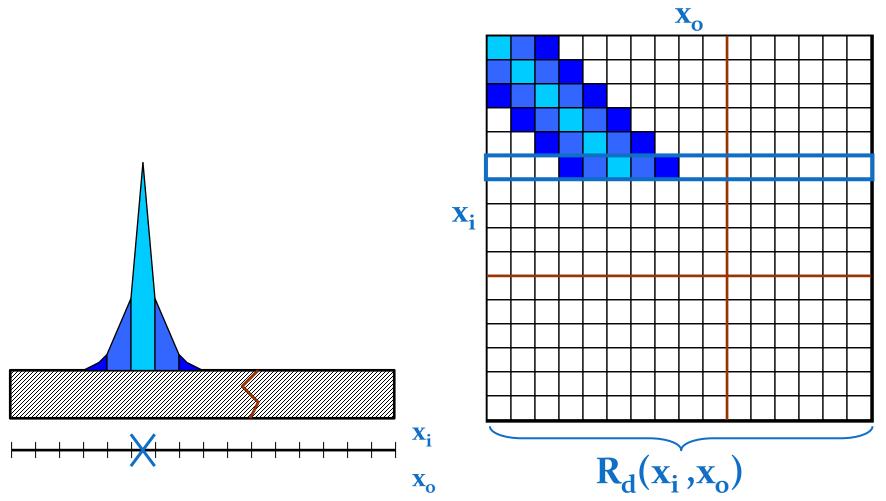




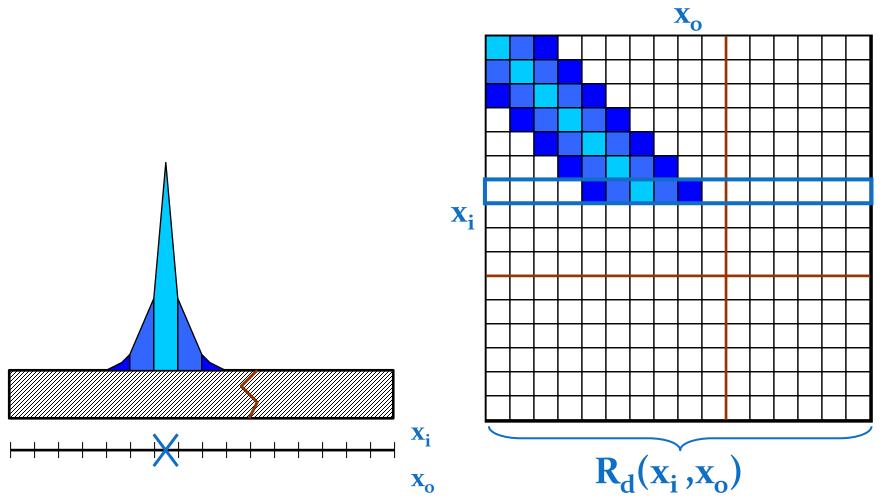




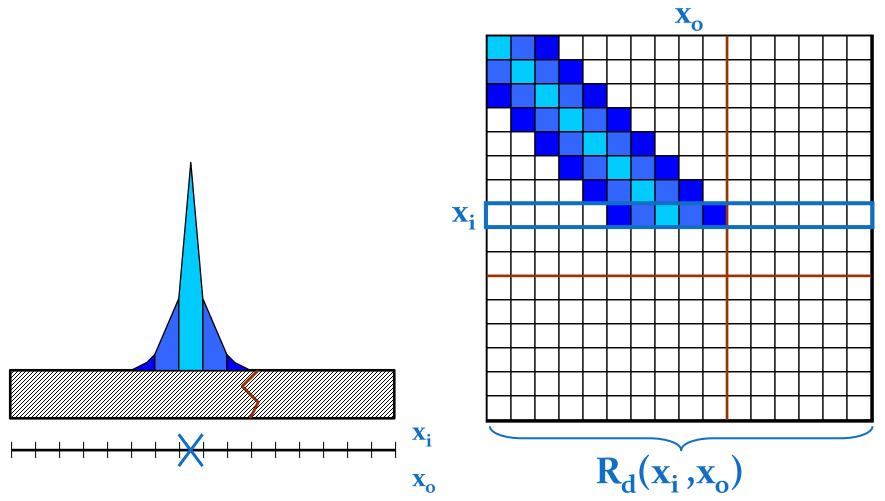




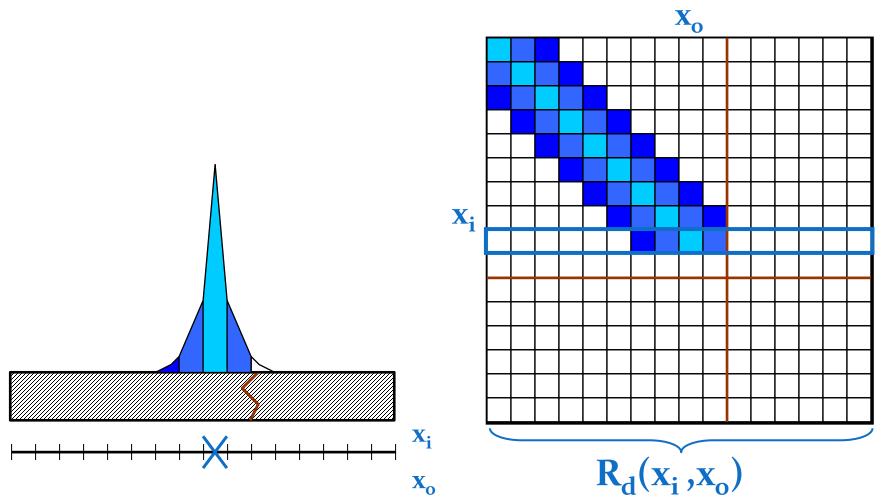




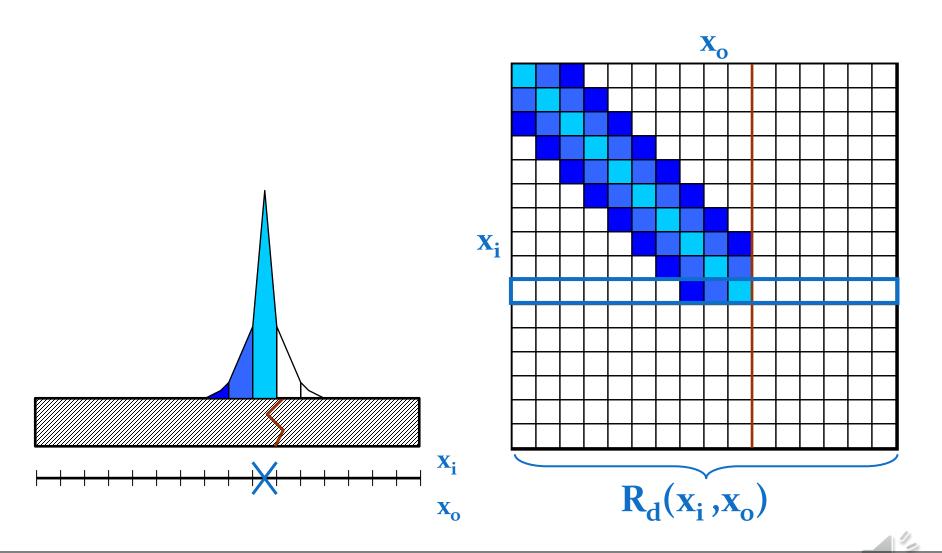




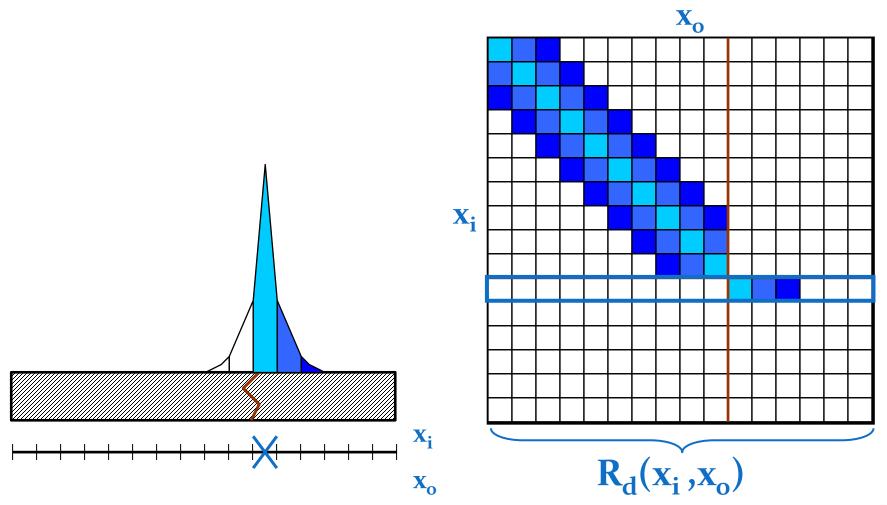




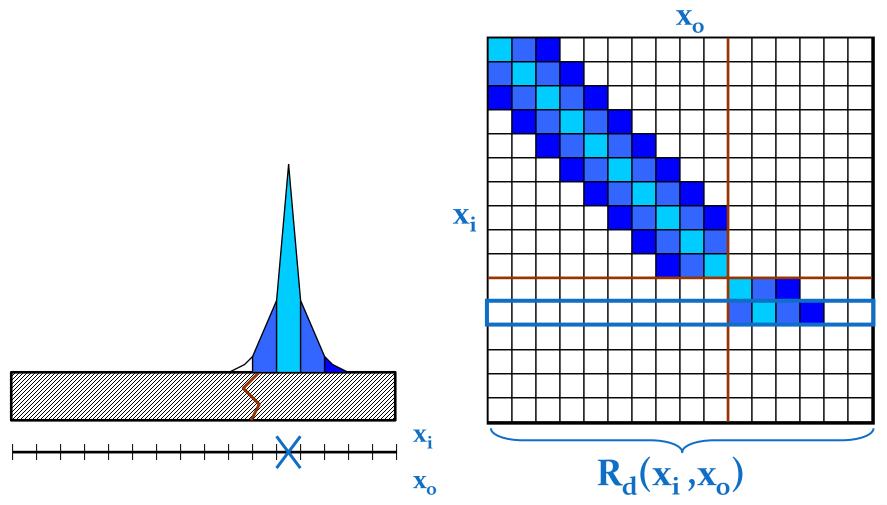




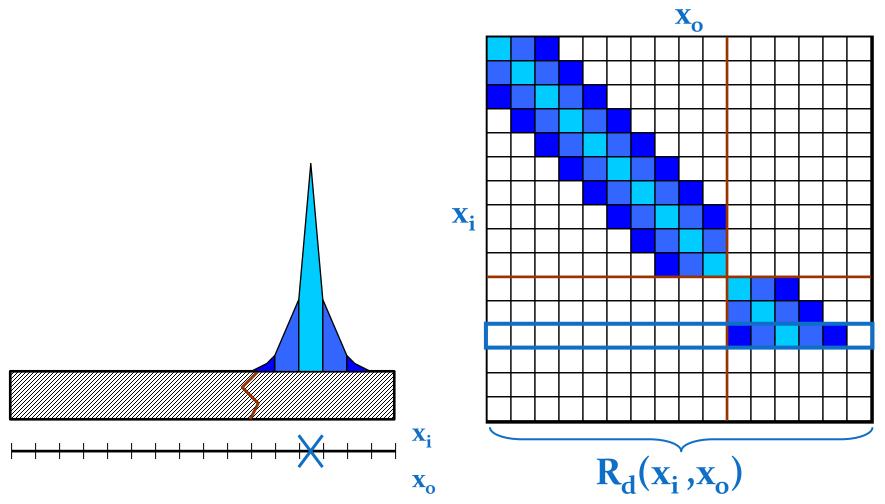
Note that when a point close to the light blocking vein is illuminated, that a part of the homogeneous response is cut off.



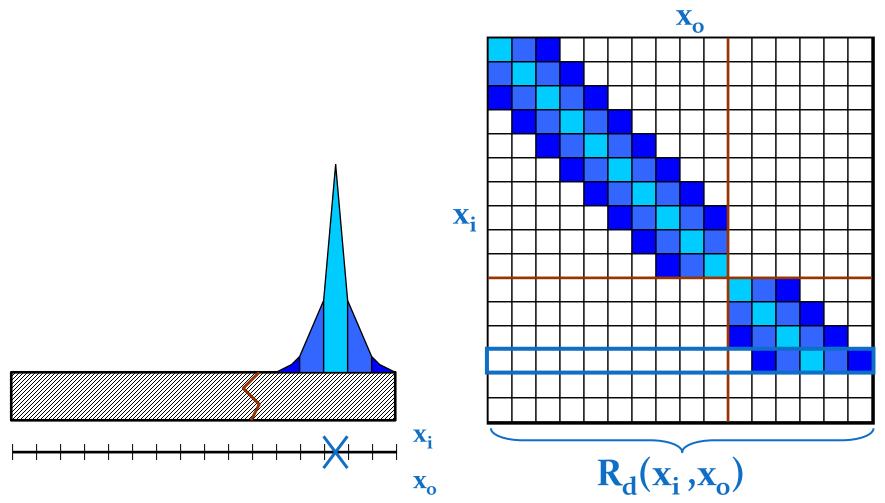




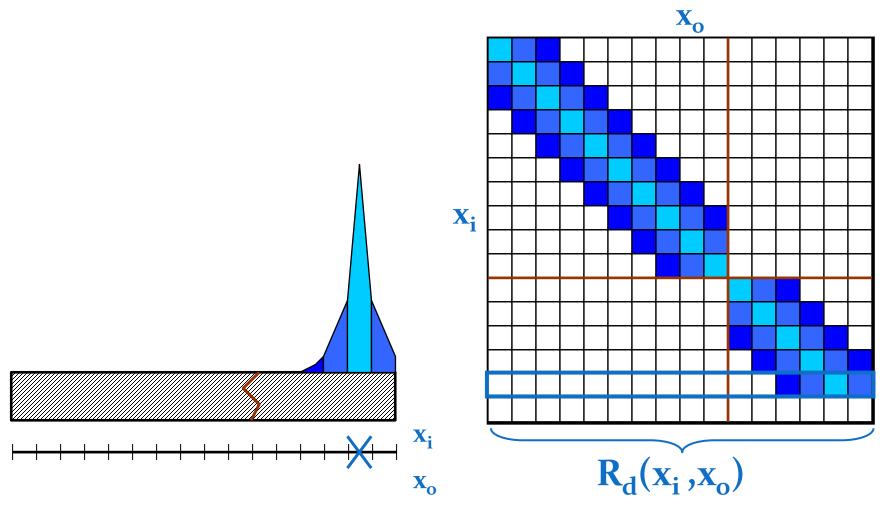




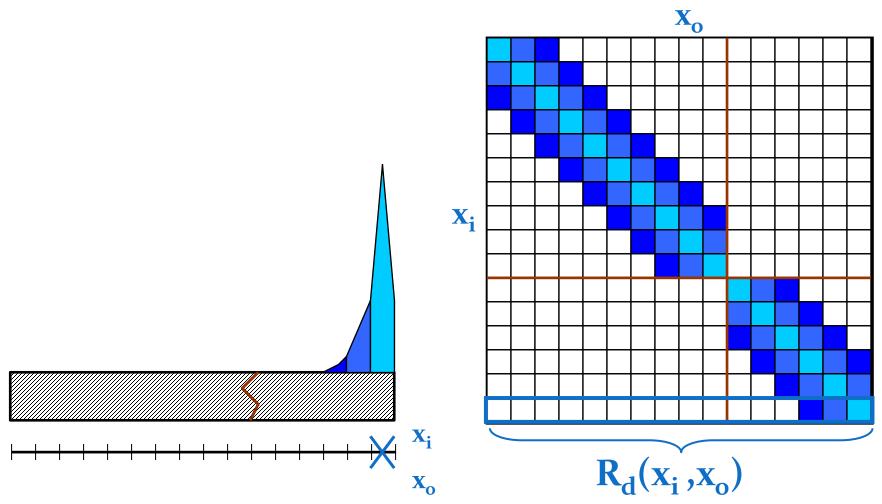






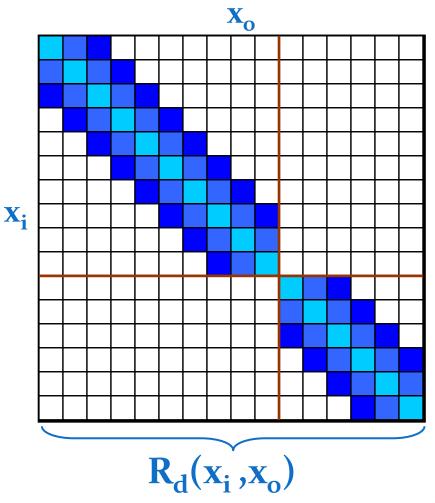








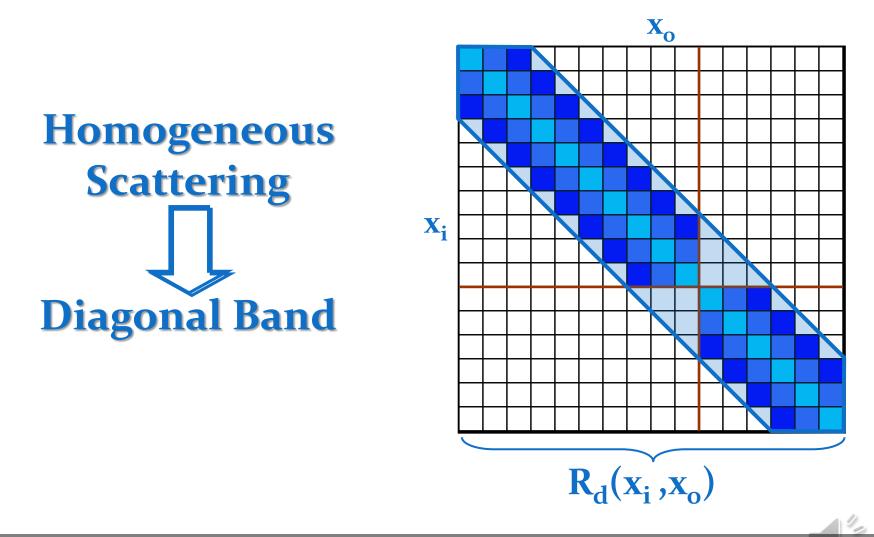
Scanning all points, yields a matrix that looks something like this.





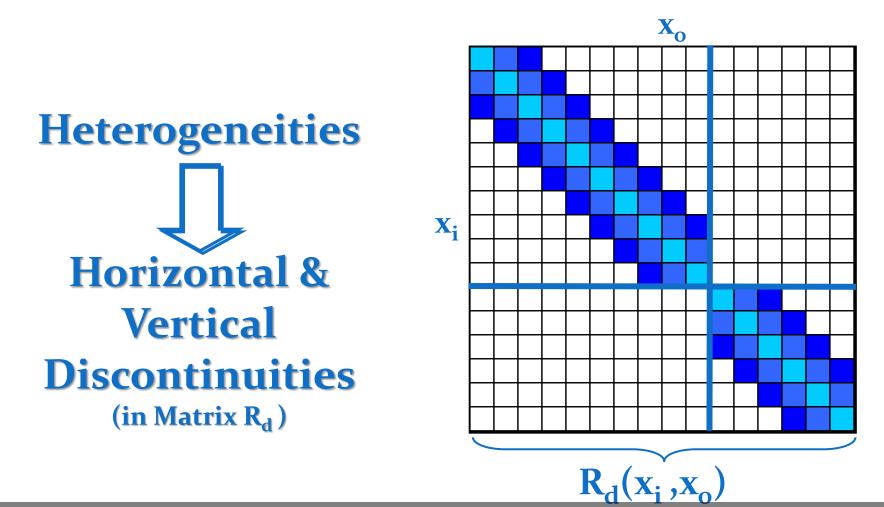
A few important observations can be made regarding the structure of this matrix.

Structure of Homogeneity



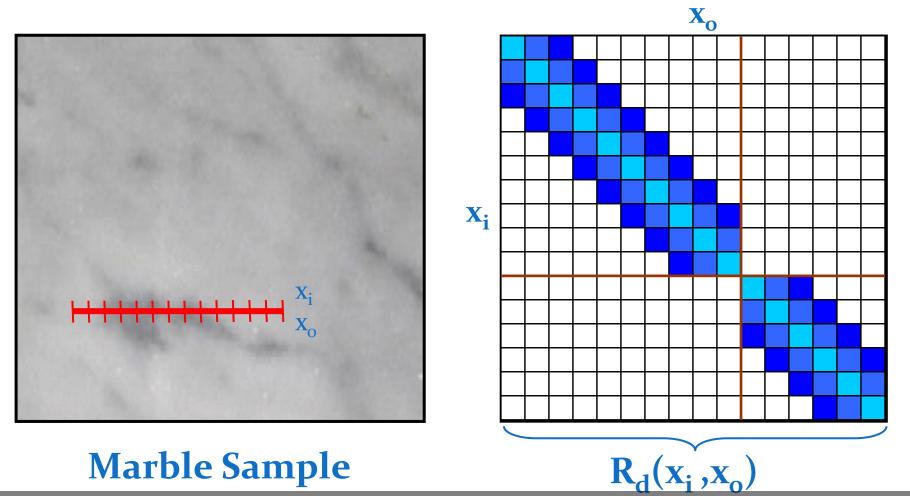
First of all, it is a band diagonal matrix. Diagonal band is the result of the homogeneous subsurface scattering. This band is interrupted by...

Structure of Heterogeneities



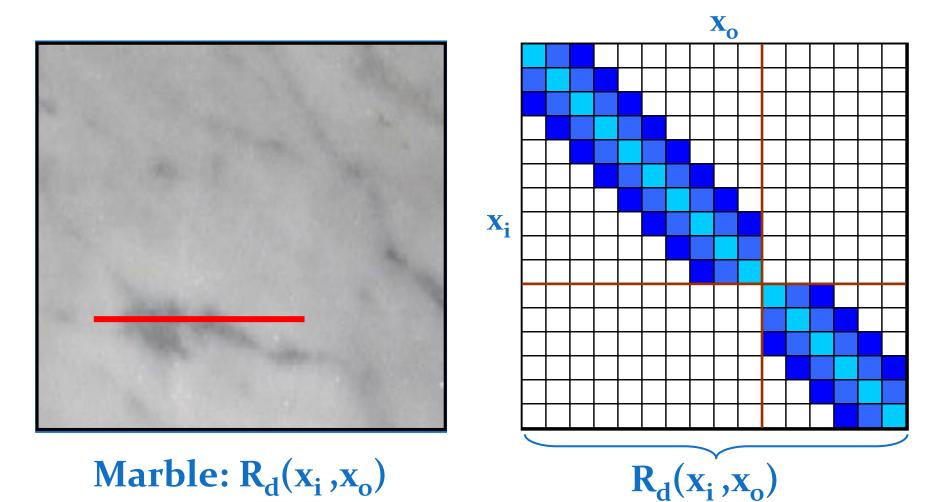
...horizontal and vertical discontinuities. These discontinuities in the matrix R_d are caused by the heterogeneity. Now, this all well for this synthetic example, but how well does this observed structure corresponds to a real subsurface scattering material.

Validation of Structure

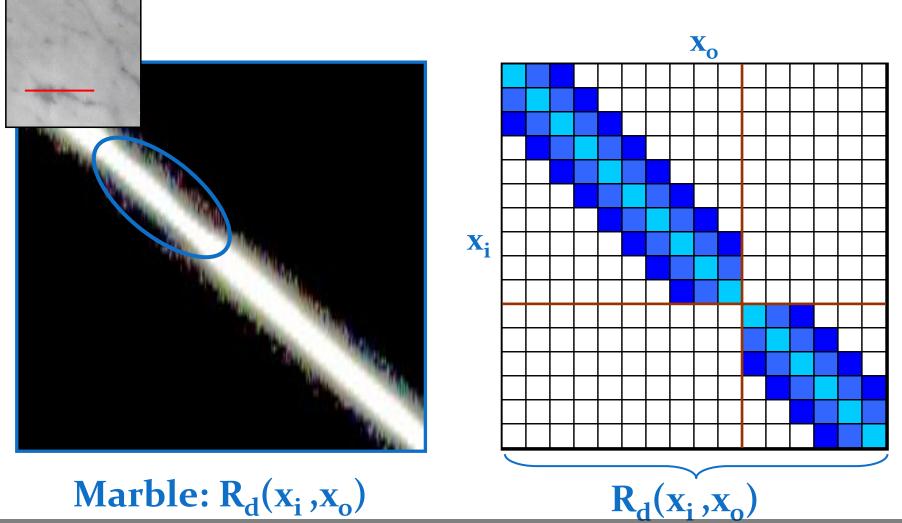


For this purpose we consider this slab of Marble. On this slab of marble, we are going to illuminate each point on this line <animate>, and are going to observe the response, also on this line.

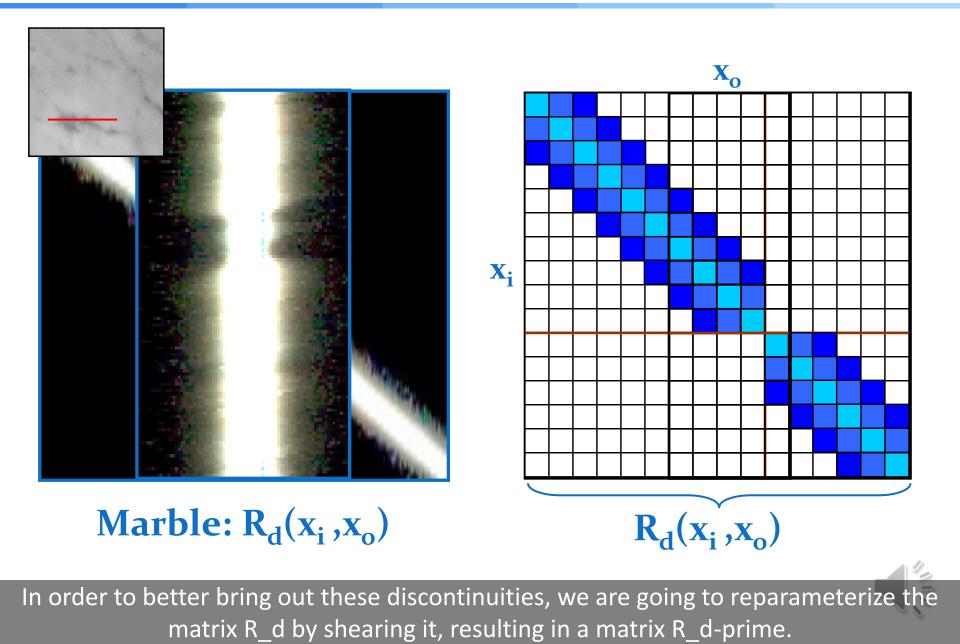
Validation of Structure

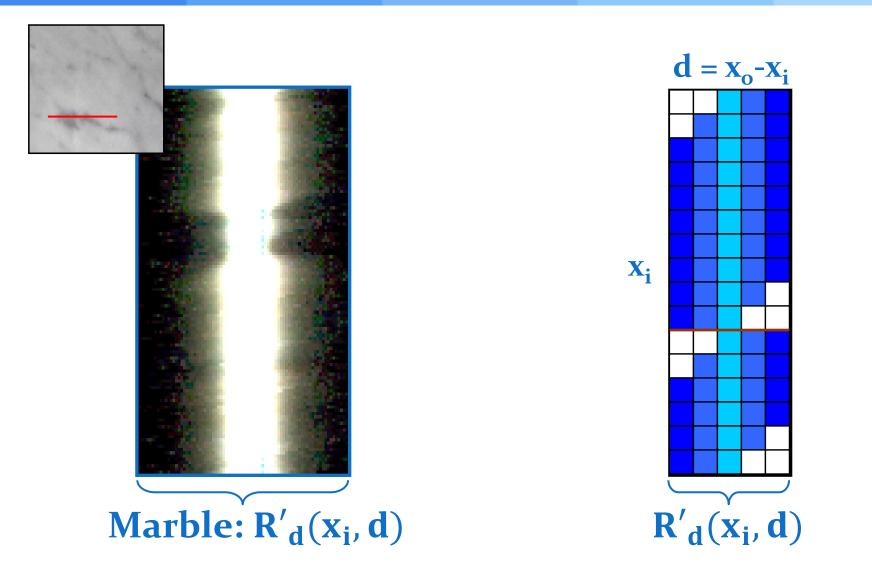


Validation of Structure



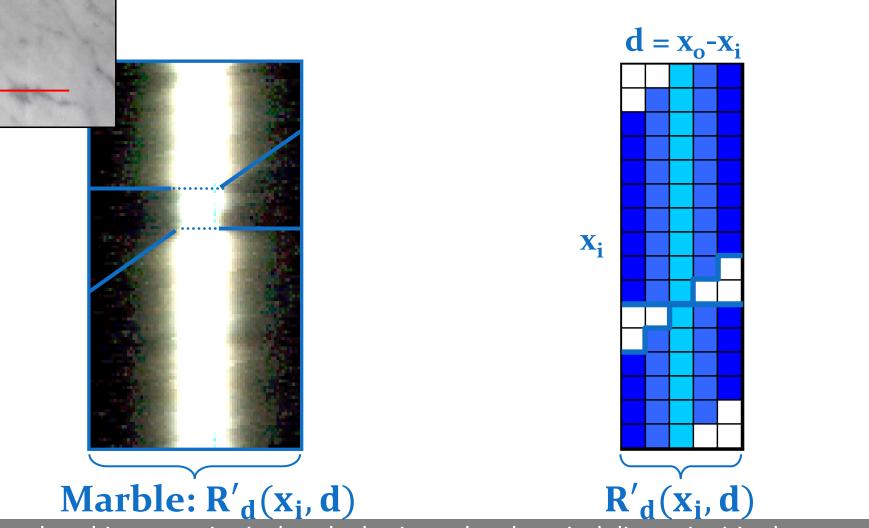
I don't know if you can see it, but the discontinuities are in the left top. The reason why these discontinuities are not as underlined as in the synthetic case, is because the veins in the marble do not block the light transport completely.



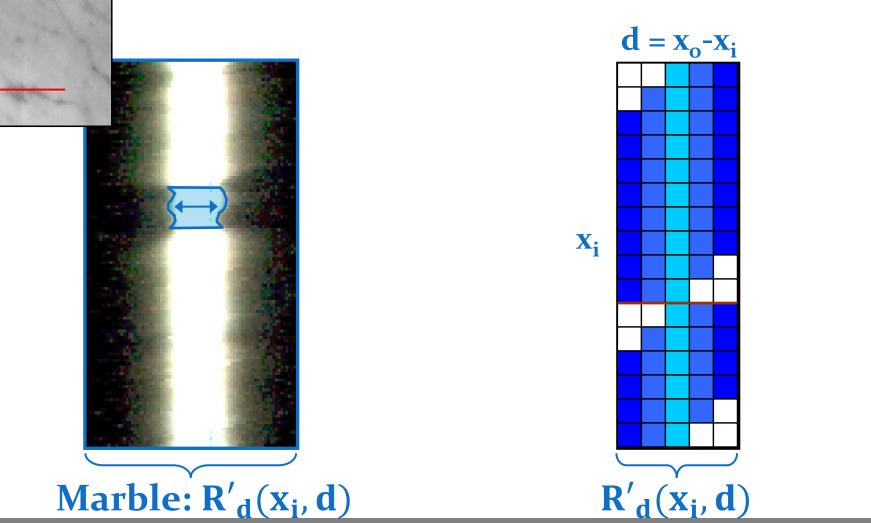




As you can see now, the discontinuities are much better visible.

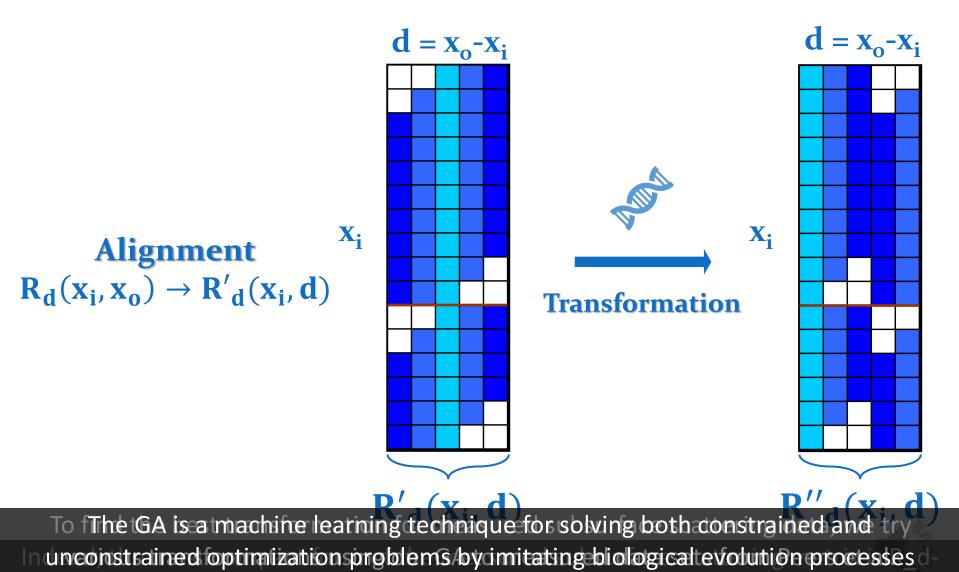


Another thing to notice is that the horizontal and vertical discontinuities have now bThis example, remprically validates our iconclusions regarding the structure in the e reparameterized bsurface scattering matrix narble sample.



Note that the width of this part in the matrix, is dependent on the amount of light blocked by the heterogeneity. Thus in case the veins would block all light, then we get a similar situation as in the synthetic example, and this region would be very thin.

Key Idea for Subsurface Scattering Modeling



We apply GA to find new transformations for real-world subsurface scattering.

Our Genetic Algorithm (1)



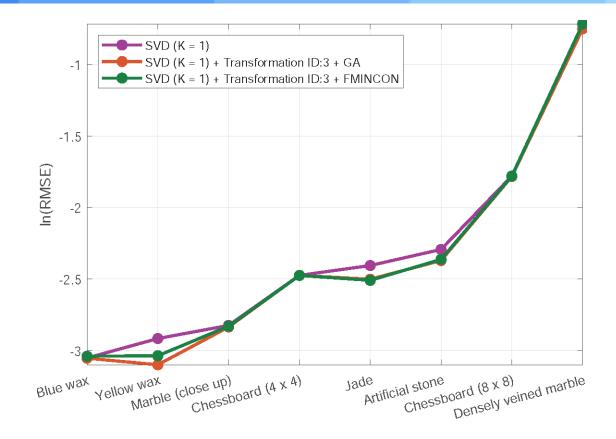
Artificial stone material

Transformation ID	Transformation expression	Chromosome	Population size	Fittest value (RMSE)
1	$R_d^{\prime\prime}(x_i,d) = \ln\left(1 + rac{R_d^{\prime}(x_i,d)}{lpha_s} ight)$	$lpha_s(R,G,B)$	30	0.09694
2	$R_d^{\prime\prime}(x_i,d) = \ln\left(lpha_d + rac{R_d^{\prime}(x_i,d)}{lpha_s} ight)$	$\alpha_d(intensity), \alpha_s(intensity)$	20	0.09699
3	$R_d''(x_i,d) = \begin{cases} R_d'(x_i,d)/max(R_d'(x_i,d)) & ifrange = 0\\ \ln\left(1 + \frac{R_d'(x_i,d)}{\alpha_s max(R_d'(x_i,d))}\right) & otherwise \end{cases}$	$\alpha_s(R,G,B), d \pm range(R,G,B)$	60	0.09340

Table 1: Properties of the genetic optimization for heterogeneous artificial stone. The table also summarizes some statistics of transformations applied by our genetic algorithm with K = 1. When we don't apply any transformations, the rank-1 approximation of

Over successive generations; the population evolves toward ap optimal solution based At each step the algorithm selecon a fitgess function.m, from the current population.

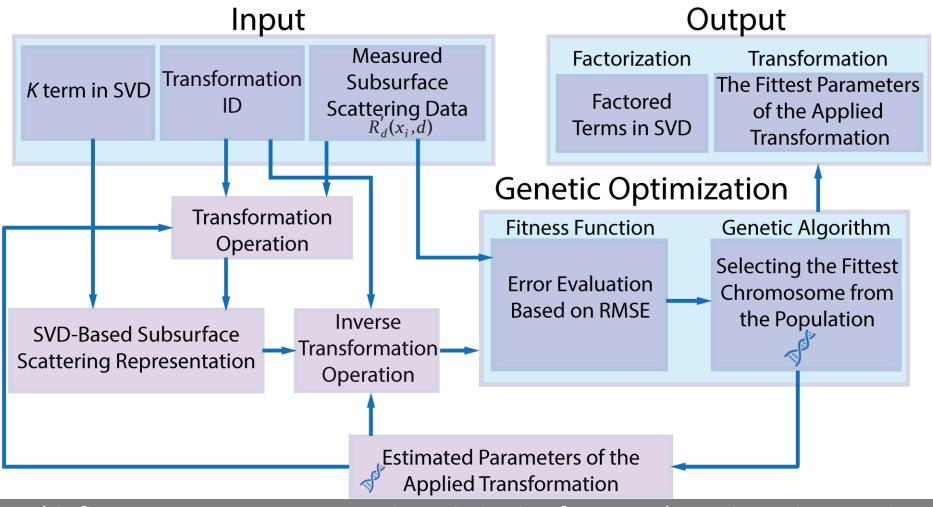
Our Genetic Algorithm (2)



A comparison of the SVD based subsurface scattering model with and without applying various optimization techniques (see Table 1). The model parameter K was selected as 1. The error values were sorted in the logarithmic RMSEs of the SVD technique (purple) for visualization purposes.

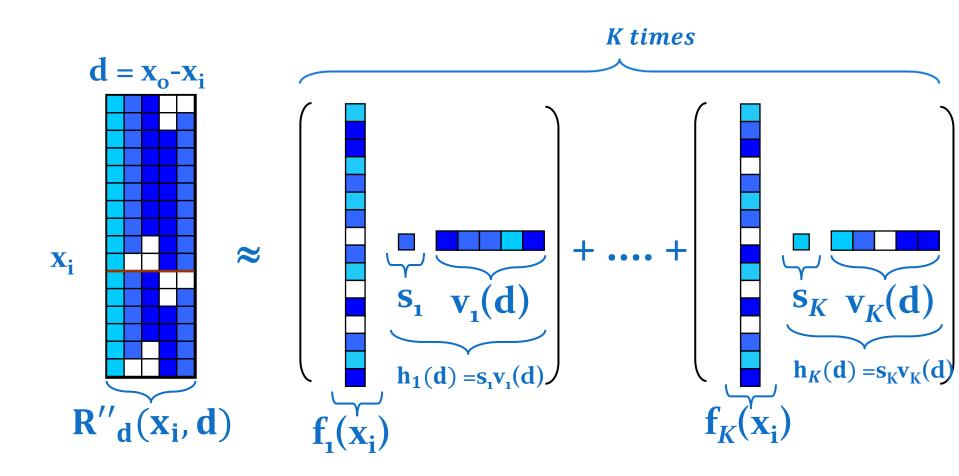
On average, transformation ID:3 with GA decreases the RMSE much more than transformation ID:3 with FMINCON Therefore, we select and use transformation ID:3 transformation. These optimizawith our GA frameworkdily available in MATLAB library.

Our Genetic Optimization Framework



In this figure, you can see our genetic optimization framework. We investigate various transformation and chromosome combinations (see Table 1) thorough our genetic optimization framework

Our Subsurface Scattering Model



Our final subsurface scattering model will be the sum of the estimation of model errors and the first factorization of R_d prime prime.

Visualization

- The full Monte Carlo path tracing implementation of MITSUBA [Jak13]:
 - *I)* Blue noise sampling of translucent object.
 - 2) The weighting of all samples, within the range of the subsurface scattering response and adding together.
 - *3)* The weighting function = the subsurface scattering representation.
- A standard texture mapping to apply a material model to a mesh.

Chessboard



To visualize our results, we implemented a rendering scheme similar to Peers et al. [PvBM06] in the Mitsuba rendering system [Jak13]. Furthermore, we used a standard texture mapping to apply a material model to a mesh.

Results – Validation

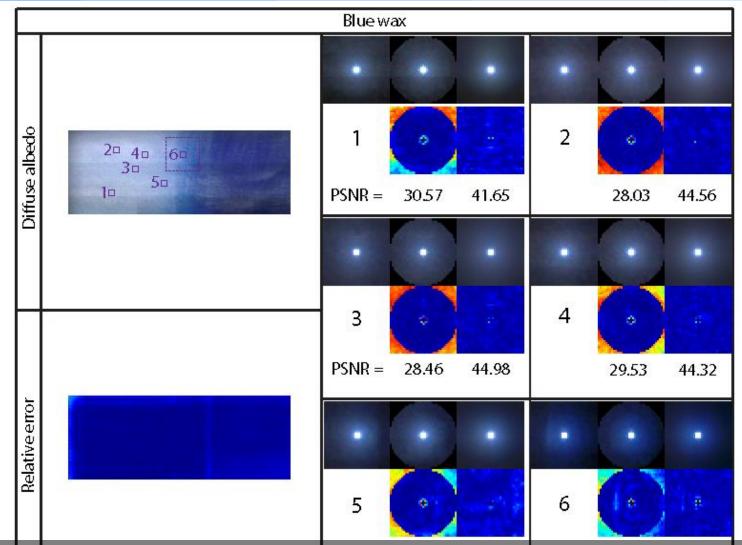
Sample material	Resolution	Kernel	Original	K	Factored	CR	RMSE
	(pixel)	size (pixel)	size		size		
Chessboard (4×4)	277×277	39×39	2.61 GB	5	8.96 MB	1/298	0.0229
Chessboard (8×8)	222×222	39×39	1.68 GB	5	5.82 MB	1/296	0.0421
Marble (close up)	128×128	39×39	570 MB	5	2.05 MB	1/278	0.0268
Densely veined marble	213×211	39×39	1.53 GB	5	5.32 MB	1/295	0.0568
Artificial stone	108×108	35×35	327 MB	5	1.48 MB	1/222	0.0340
Blue wax	88×232	35×35	572 MB	5	2.48 MB	1/231	0.0192
Jade	260×260	35×35	1.85 GB	5	7.88 MB	1/240	0.0398
Yellow wax	110×110	39×39	421 MB	5	1.56 MB	1/270	0.0225

Table 2: Properties of the factored heterogeneous subsurface scattering materials. The table also summarizes some statistics of our GA based subsurface scattering model with typically selected values for *K*.



We validate our model on 8 different real-world translucent materials. This table gives an overview of the modeled heterogeneous translucent materials and lists a number of statistics for our model, based on typical values for K.

Results - Comparisons (1)



The SubEdit [STPP09] representation may show radially symmetric behavior at some materials, due to the parametrization used, which may be insufficient for representing We compare measured aheterogeneous materials accurately relected surface points.

Results - Comparisons (2)

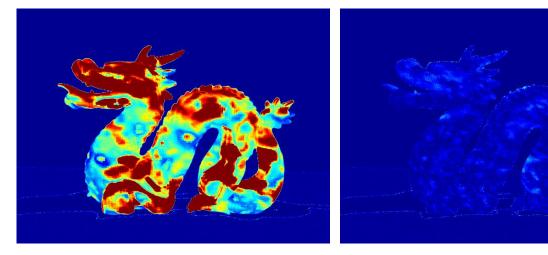


(Storage: 327 MB)

(Storage: 3.29 MB)

(Storage: 2.94 MB)





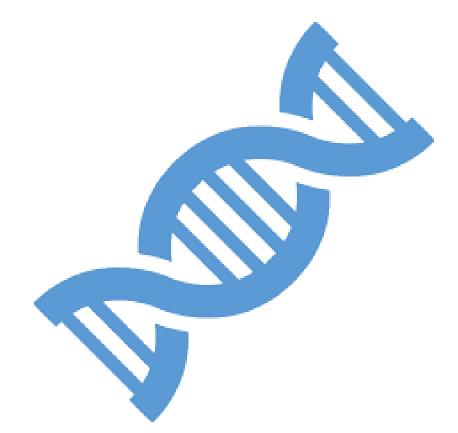
Reference imageSubEdit ModelOur Model (K=10)The comparisons coultined show that (OGN model represents heterogeneous 4 translucentmaterials more accurately for comparable data storage requirements.

Conclusions

- A GA based heterogeneous subsurface scattering model.
- Apply to any geometry.
- Integrate into a standard physically-based rendering system easily.
- We plan to investigate real-time rendering algorithms to implement our representation in screen-space.

In the future, we plan to investigate real-time rendering algorithms to implement our In this work, we present representation incscreen-spacesurface scattering model.

Thank You...





I hope you enjoyed this presentation, and I thank you for your attention.